

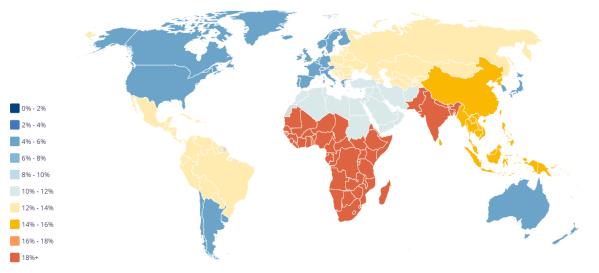
### **CamVisors:** A Low-Cost Smart Glass System Utilizing Computer Vision for the Blind

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## Background

- Over 40 million suffer from blindness worldwide
- ✤ 300 million suffer from severe vision loss
- ✤ Mostly in developing countries in Asia and Africa

Age-std prevalence of all vision loss by GBD Super Region 2020 (all ages, males & females)



Source: Data from VLEG/GBD 2020 model, accessed via the IAPB Vision Atlas

- White canes are **flawed** and require training
- Current innovations are expensive and inaccessible



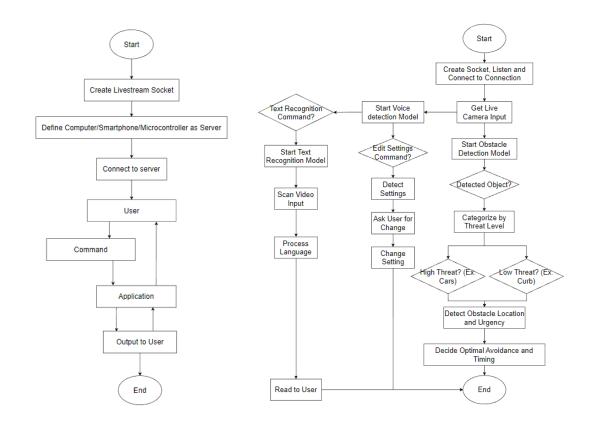
- Computer vision-based system
- Developed for affordability and accessibility

World Health Organization. (n.d.). World Report on vision. World Health Organization. Retrieved February 13, 2023, from https://www.who.int/publications/i/item/9789241516570

Kim, Dae, et al. "Travel in Adverse Winter Weather Conditions by Blind Pedestrians: Effect of Cane Tip Design on Travel on Snow." *Journal of Visual Impairment & Blindness*, vol. 110, no. 1, 2016, p. 53,

# Methodology

- Client-Server style architecture
- Utilize smartphone to run computer vision models
- ✤ Livestream camera to send input to server



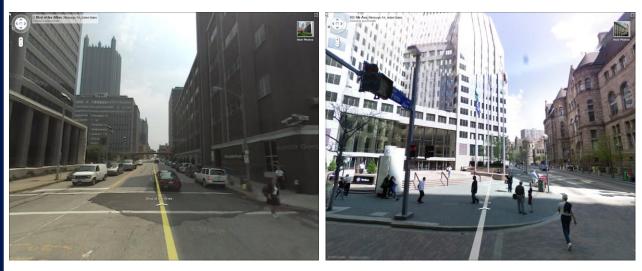
- Tested and compared 7 livestream cameras
- Compatible with iOS, Android, and others
- ✤ Localization of models to ensure usability



## Methodology (cont.)

- Trained on NVIDIA GTX 1660
  - ✤ 1408 CUDA & 6 GB VRAM
- ✤ Used TensorFlow and TFLite for mobile
- Used a Google Street View **dataset** in training
- Prevented overfitting by training on COCO
- Weighted obstacles by danger level
- ✤ Used OpenCV to estimate distance
- \* **Region-based** path detection
- Calculated ideal user path through modified
  Dijkstra's algorithm





Lin, T., Maire, M., Belongie, S., Bourdev, L., Girshick, R., Hays, J., Perona, P., Ramanan, D., Zitnick, C. L., & Dollár, P. (2014). Microsoft COCO: Common Objects in Context. ArXiv. /abs/1405.0312

Amir Roshan Zamir and Mubarak Shah, "Image Geo-localization Based on Multiple Nearest Neighbor Feature Matching using Generalized Graphs", IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI), 2014

## Results

- ✤ Highly accurate **object** and **distance** recognition
- ✤ 2-ounce camera with a total cost under \$200
- Compatible with current approaches

	Samples	Percentages
Baseline	1126	
Detection Recall	1120	99.5%
Missed	6	0.5%
True Classification	1058	94.5%
False Classification	62	5.5%



All information is read to the user, these are visualizations of the models for demonstrative purposes



- The system costs 95% less than most current computer vision-based solutions
- ✤ Accuracy over 90% in all models
- Detailed obstacle avoidance directions, surrounding information

#### **Future Applications**

- \* Affordable, accessible, and comfortable assistance system
- Can easily be mass manufactured and distributed
- Potential to impact the lives of over 40 million blind individuals and over 300 million visually impaired
- \* Add more features such as **navigation**, currency counting, and **touch-enabled** commands

# **Thank You!**

#### References

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All images, graphs, tables, and data generated by Matthew Yao unless otherwise stated.

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